

Modeling DNA structure, elasticity, and deformations at the base-pair level

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We present a generic model for DNA at the base-pair level. We use a variant of the Gay-Berne potential to represent the stacking energy between the neighboring base pairs. The sugar-phosphate backbones are taken into account by semirigid harmonic springs with a nonzero spring length. The competition between these two interactions and the introduction of a simple geometrical constraint lead to a stacked right-handed *B*-DNA-like conformation. The mapping of the presented model to the Marko-Siggia and the stack-of-plates model enables us to optimize the free model parameters so as to reproduce the experimentally known observables such as persistence lengths, mean and mean-squared base-pair step parameters. For the optimized model parameters, we measured the critical force where the transition from *B*- to *S*-DNA occurs to be approximately 140 pN. We observe an overstretched *S*-DNA conformation with highly inclined bases which partially preserves the stacking of successive base pairs.

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I. INTRODUCTION

Following the discovery of the double helix by Watson and Crick [1], the structure and elasticity of DNA has been investigated on various length scales. The x-ray-diffraction studies of single crystals of DNA oligomers have led to a detailed picture of the possible DNA conformations [2,3] with atomistic resolution. Information on the behavior of DNA on larger scales is accessible through nuclear magnetic resonance [4] and various optical methods [5,6], such as video [7] and electron microscopy [8]. An interesting development of the last decade is the nanomechanical experiments with *individual* DNA molecules [9–13] which, for example, reveal the intricate interplay of supercoiling on large length scales and local denaturation of the double-helical structure.

The experimental results are usually rationalized in the framework of two types of models: base-pair steps and variants of the continuum elastic wormlike chain. The first, more local, approach describes the relative location and orientation of the neighboring base pairs in terms of intuitive parameters such as twist, rise, slide, roll, etc., [14–17]. In particular, it provides a mechanical interpretation of the biological function of particular sequences [18]. The second approach models DNA on length scales beyond the helical pitch as a wormlike chain (WLC) with empirical parameters describing the resistance to bending, twisting, and stretching [19,20]. The results are in remarkable agreement with the nanomechanical experiments mentioned above [21]. WLC models are commonly used in order to address biologically important phenomena such as supercoiling [22–24] or the wrapping of DNA around histones [25]. In principle, the two descriptions of DNA are linked by a systematic coarse-graining procedure. From the given (average) values of rise, twist, slide, etc., one can reconstruct the shape of the corresponding helix on large scales [14,18,26]. Similarly, the elastic constant characterizing the continuum model is related to the

local elastic energies in a stack-of-plates model [27].

Difficulties are encountered in situations which cannot be described by a linear response analysis around the undisturbed (*B*-DNA) ground state. This situation arises regularly during cellular processes and is therefore of considerable biological interest [18]. A characteristic feature, observed in many nanomechanical experiments, is the occurrence of plateaus in force-elongation curves [10,11,13]. These plateaus are interpreted as structural transitions between the microscopically distinct states. While atomistic simulations have played an important role in identifying the possible local structures such as *S*- and *P*-DNA [11,13], this approach is limited to relatively short DNA segments containing several dozen base pairs. The behavior of longer chains is interpreted on the basis of stack-of-plates model with step-type dependent parameters and free energy penalties for non-*B* steps. Realistic force-elongation curves are obtained by a suitable choice of parameters and as the consequence of constraints for the total extension and twist (or their conjugate forces) [28]. Similar models, describing the nonlinear response of *B*-DNA to stretching [29] or untwisting [30,31], predict stability thresholds for *B*-DNA due to a combination of more realistic, short-range interaction potentials for rise with twist-rise coupling enforced by the sugar-phosphate backbones.

Clearly, the agreement with the experimental data will increase with the amount of details which is properly represented in a DNA model. However, there is a strong evidence both from atomistic simulations [32] as well as from the analysis of oligomer crystal structures [33] that the base-pair level provides a sensible compromise between the conceptual simplicity, the computational cost, and the degree of reality. While Lavery and co-workers [32] have shown that the base pairs effectively behave as rigid entities, the results of Hassan and Calladine [33] and of Hunter and co-workers [34,35] suggest that the dinucleotide parameters observed in oligomer crystals can be understood as a consequence of van der Waals and electrostatic interactions between the neighboring base pairs and constraints imposed by the sugar-phosphate backbone.

The purpose of the present paper is to propose of a class

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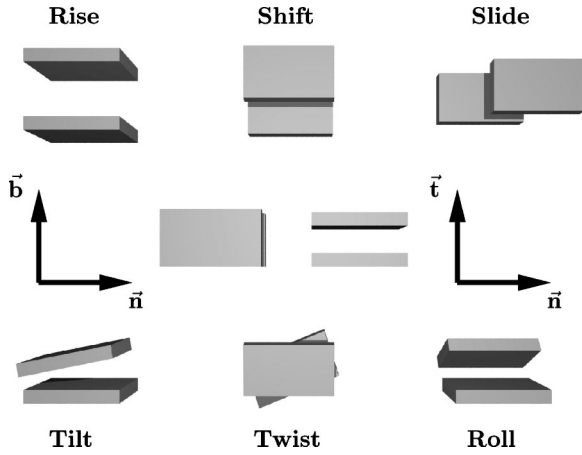


FIG. 1. Illustration of all six base-pair parameters and the corresponding coordinate system.

of “DNA-like” molecules with simplified interactions resolved at the base or base-pair level. In order to represent the stacking interactions between the neighboring bases (base pairs), we use a variant [36] of the Gay-Berne (GB) potential [37] used in the studies of discotic liquid crystals. The sugar-phosphate backbones are reduced to semirigid springs connecting the edges of the disks/ellipsoids. Using Monte Carlo (MC) simulations, we explore the local stacking and the global helical properties as functions of the model parameters. In particular, we measure the effective parameters needed to describe our systems in terms of stack-of-plates (SOP) and wormlike chain models, respectively. This allows us to construct DNA models which properly represent the equilibrium structure, fluctuations, and linear response. At the same time, we preserve the possibility of local structural transitions, e.g., in response to the external forces.

The paper is organized as follows. In Sec. II, we introduce the base-pair parameters to discuss the helix geometry in terms of these variables. Furthermore, we discuss how to translate the base-pair parameters in macroscopic variables such as bending and torsional rigidity. In Sec. III, we propose a model and discuss the methods (MC simulation, energy minimization) we use to explore its behavior. In Sec. IV, we present the resulting equilibrium structures, the persistence lengths as a function of the model parameters, and the behavior under stretching.

II. THEORETICAL BACKGROUND

A. Helix geometry

To resolve and interpret the x-ray-diffraction studies on DNA oligomers, the relative position and orientation of successive base pairs are analyzed in terms of rise (Ri), slide (Sl), shift (Sh), twist (Tw), roll (Ro), and tilt (Ti) [38] (see Fig. 1). In order to illustrate the relation between these local parameters and the overall shape of the resulting helix, we discuss a simple geometrical model in which DNA is viewed as a twisted ladder in which all bars lie in one plane. For vanishing bending angles with $Ro=Ti=0$, each step is characterized by four parameters: Ri, Sl, Sh, and Tw [18]. Within the given geometry, a base pair can be characterized by its

position \mathbf{r} and the angle of its main axis with the \mathbf{n}/\mathbf{b} axis (\mathbf{n} points to the direction of the large axis, \mathbf{b} points to the direction of the small axis, and \mathbf{t} , representing the tangent vector of the resulting helix, is perpendicular to the $\mathbf{n}-\mathbf{b}$ plane as it is illustrated in Fig. 1). At each step the center points are displaced by a distance $\sqrt{Sl^2+Sh^2}$ in the $\mathbf{n}-\mathbf{b}$ plane. The angle between the successive steps is equal to the twist angle, and the center points are located on a helix with radius $r = \sqrt{Sl^2+Sh^2}/[2 \sin(Tw/2)]$.

In the following, we study the consequences of imposing a simple constraint on the bond lengths l_1 and l_2 representing the two sugar-phosphate backbones (the rigid bonds connect the right and left edges of the bars along the \mathbf{n} axis, respectively). Ri is the typical height of a step which we will try to impose on the grounds that it represents the preferred stacking distance of the neighboring base pairs. We choose $Ri = 3.3 \text{ \AA}$ corresponding to the B-DNA value. One possibility to fulfill the constraint $l_1=l_2=l=6 \text{ \AA}$ is a pure twist. In this case, a relationship between the twist angle, the width of the base pairs d , the backbone length l , and the imposed rise is obtained:

$$Tw = \arccos\left(\frac{d^2 - 2l^2 + 2Ri^2}{d^2}\right). \quad (1)$$

Another possibility is to keep the rotational orientation of the base pair ($Tw=0$), but to displace its center in the $\mathbf{n}-\mathbf{b}$ plane, in which case $Ri^2 + Sl^2 + Sh^2 = l^2$. With $Sh=0$, it results in a skewed ladder with skew angle $\arcsin(Sl/l)/\pi$ [18].

The general case can be solved as well. In the first step, a general condition is obtained which needs to be fulfilled by any combination of Sh, Sl, and Tw independently of Ri. For nonvanishing Tw, this yields a relation between Sh and Sl:

$$\tan(Tw) = \frac{Sh}{Sl}. \quad (2)$$

Using Eq. (2), the general equation can finally be solved as:

$$Sl = \frac{1}{\sqrt{2}} \left[\cos\left(\frac{Tw}{2}\right)^2 \sqrt{\sec\left(\frac{Tw}{2}\right)^2 (2l^2 - d^2 - Ri^2)} \right]. \quad (3)$$

Equation (3) is the result of the mechanical coupling of slide, shift, and twist due to the backbones. Treating the rise again as a constraint, the twist is reduced for increasing slide or shift motion. The center-center distance c between the two neighboring base pairs is given by

$$c = \sqrt{Ri^2 + Sl^2 [1 + \tan^2(Tw)]}. \quad (4)$$

For $Tw=0$ and a given value of Ri, the center-center distance is equal to the backbone length l , and for $Tw = \arccos[(d^2 - 2l^2 + 2Ri^2)/d^2]$ one obtains $c=Ri$.

B. Thermal fluctuations

In this section, we discuss how to calculate the effective coupling constants of a harmonic system, valid within the linear response theory, describing the couplings of the base-

pair parameters along the chain. Furthermore, we show how to translate the measured mean and mean-squared values of the six microscopic base-pair parameters into macroscopic observables such as bending and torsional persistence length. This provides the linkage between the two descriptions: WLC versus SOP model.

Within the linear response theory, it should be possible to map our model onto a Gaussian system where all translational and rotational degrees of freedom are harmonically coupled. We refer to this model as the SOP model [27]. The effective coupling constants are given by the second derivatives of the free energy in terms of base-pair variables around the equilibrium configuration. This yields 6×6 matrices \mathcal{K}^{nm} , describing the couplings of the base-pair parameters of the neighboring base pairs along the chain:

$$\mathcal{K}^{nm} = \frac{\partial^2 \mathcal{F}}{\partial x_i^n \partial x_j^m}. \quad (5)$$

Therefore one can calculate the $(N-1) \times (N-1)$ correlation matrix \mathcal{C} in terms of base-pair parameters, where N is thereby the number of base pairs:

$$\langle \mathcal{C} \rangle = \begin{pmatrix} \mathcal{K}^{11} & \mathcal{K}^{12} & \mathcal{K}^{13} & \mathcal{K}^{14} & \dots \\ \mathcal{K}^{12} & \mathcal{K}^{22} & \mathcal{K}^{23} & \mathcal{K}^{24} & \dots \\ & & \ddots & & \\ & & & \ddots & \end{pmatrix}^{-1}. \quad (6)$$

The inversion of \mathcal{C} results in a generalized connectivity matrix with effective coupling constants as entries.

The following considerations are based on the assumption that one only deals with nearest-neighbor interactions. Then the successive base-pair steps are independent of each other, and the calculation of the orientational correlation matrix becomes feasible. In the absence of spontaneous displacements ($Sl=Sh=0$) and spontaneous bending angles ($Ti=Ro=0$), as it is in the case for *B*-DNA, going from one base pair to the neighboring implies three operations. In order to be independent of the reference base pair, one first rotates the respective base pair into the midframe with $\mathcal{R}(Tw_{sp}/2)$ (\mathcal{R} is a rotation matrix, Tw_{sp} denotes the spontaneous twist), followed by a subsequent overall rotation in the midframe,

$$\mathcal{A} = \begin{pmatrix} \mathbf{t}_i \cdot \mathbf{t}_{i+1} & \mathbf{t}_i \cdot \mathbf{b}_{i+1} & \mathbf{t}_i \cdot \mathbf{n}_{i+1} \\ \mathbf{b}_i \cdot \mathbf{t}_{i+1} & \mathbf{b}_i \cdot \mathbf{b}_{i+1} & \mathbf{b}_i \cdot \mathbf{n}_{i+1} \\ \mathbf{n}_i \cdot \mathbf{t}_{i+1} & \mathbf{n}_i \cdot \mathbf{b}_{i+1} & \mathbf{n}_i \cdot \mathbf{n}_{i+1} \end{pmatrix}, \quad (7)$$

taking into account the thermal motions of Ro , Ti , and Tw , and a final rotation due to the spontaneous twist $\mathcal{R}(Tw_{sp}/2)$. The orientational correlation matrix between the two neighboring base pairs can be written as $\langle \mathcal{O}_{i+1} \rangle = \mathcal{R}(Tw_{sp}/2) \langle \mathcal{A} \rangle \mathcal{R}(Tw_{sp}/2)$. \mathcal{A} describes the fluctuations around the mean values. As a consequence of the independence of the successive base-pair parameters, one finds $\langle \mathcal{O}_{i+j} \rangle = (\mathcal{R}(Tw_{sp}/2) \langle \mathcal{A} \rangle \mathcal{R}(Tw_{sp}/2))^j$, where the matrix product is carried out in the eigenvector basis of $\mathcal{R}(Tw_{sp}/2) \langle \mathcal{A} \rangle \mathcal{R}(Tw_{sp}/2)$. In the end, one finds a relationship between the mean and mean-squared local base-pair parameters

and the bending and torsional persistence length. The calculation yields an exponentially decaying tangent-tangent correlation function $\langle \mathbf{t}(0) \cdot \mathbf{t}(s) \rangle = \exp(-s/l_p)$ with a bending persistence length

$$l_p = \frac{2 \langle Ri \rangle}{(\langle Ti^2 \rangle + \langle Ro^2 \rangle)}. \quad (8)$$

In the following, we will calculate the torsional persistence length. Making use of a simple relationship between the local twist and the base-pair orientations turns out to be more convenient than the transfer matrix approach.

The (bi)normal-(bi)normal correlation function is an exponentially decaying function with an oscillating term depending on the helical repeat length $h = p \langle Ri \rangle$ and the helical pitch $p = 2\pi / \langle Tw \rangle$, respectively, namely $\langle \mathbf{n}(0) \cdot \mathbf{n}(s) \rangle = \exp(-s/l_n) \cos(2\pi s/h)$. The torsional persistence length $l_n = l_b$ can be calculated in the following way. It can be shown that the twist angle Tw of two successive base pairs is related to the orientations $\{\mathbf{t}, \mathbf{b}, \mathbf{n}\}$ and $\{\mathbf{t}', \mathbf{b}', \mathbf{n}'\}$ through

$$\cos(Tw) = \frac{\mathbf{n} \cdot \mathbf{n}' + \mathbf{b} \cdot \mathbf{b}'}{1 + \mathbf{t} \cdot \mathbf{t}'}. \quad (9)$$

Taking the mean and using the fact that the orientational correlation functions and the twist correlation function decay exponentially,

$$\exp(-1/l_{Tw}) = \frac{2 \exp(-1/l_n)}{1 + \exp(-1/l_p)}, \quad (10)$$

yields in the case of stiff filaments a simple expression of l_n depending on l_p and l_{Tw} :

$$\frac{l_n}{2} = \frac{l_b}{2} = \left(\frac{2}{l_{Tw}} + \frac{1}{l_p} \right)^{-1}, \quad (11)$$

where the twist persistence length is defined as

$$l_{Tw} = \frac{\langle Ri \rangle}{\langle Tw^2 \rangle}. \quad (12)$$

III. MODEL AND METHODS

Qualitatively, the geometrical considerations suggest a *B*-DNA-like ground state and the transition to a skewed ladder conformation under the influence of a sufficiently high stretching force, because this provides the possibility to lengthen the chain and to partially conserve stacking. Quantitative modeling requires the specification of a Hamiltonian.

A. Introduction of the Hamiltonian

The observed conformation of a dinucleotide base-pair step represents a compromise between (i) the base stacking interactions (bases are hydrophobic and the base pairs (bp) can exclude water by closing the gap in between them) and (ii) the preferred backbone conformation (the equilibrium backbone length restricts the conformational space accessible

to the base pairs) [39]. Packer and Hunter [39] have shown that roll, tilt, and rise are backbone-independent parameters. They depend mainly on the stacking interaction of the successive base pairs. In contrast, the twist is solely controlled by the constraints imposed by a rigid backbone. Slide and shift are sequence dependent. While it is possible to introduce sequence-dependant effects into our model, they are ignored in the present paper.

In the present paper, we propose a generic model for DNA where the molecule is described as a stack of thin, rigid ellipsoids representing the base pairs (Fig. 2). The shape of the ellipsoids is given by three radii a, b, c of the main axes in the body frames, which can be used to define a structure matrix

$$\mathbf{S} = \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{pmatrix}, \quad (13)$$

where $2a$ corresponds to the thickness, $2b$ to the depth which is a free parameter in the model, and $2c = 18 \text{ \AA}$ to the width of the ellipsoid which is fixed to the diameter of a *B*-DNA helix. The thickness $2a$ will be chosen in such a way that the minimum center-center distance for perfect stacking reproduces the experimentally known value of 3.3 \AA .

The attraction and the excluded volume between the base pairs are modeled by a variant of the GB potential [36,37] for ellipsoids of arbitrary shape \mathbf{S}_i , relative position \vec{r}_{12} , and orientation \mathbf{A}_i . The potential can be written as a product of three terms:

$$\begin{aligned} U(\mathbf{A}_1, \mathbf{A}_2, \vec{r}_{12}) \\ = U_r(\mathbf{A}_1, \mathbf{A}_2, \vec{r}_{12}) \eta_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}) \chi_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}). \end{aligned} \quad (14)$$

The first term controls the distance dependence of the interaction and has the form of a simple Lennard-Jones potential,

$$U_r = 4\epsilon_{\text{GB}} \left[\left(\frac{\sigma}{h + \gamma\sigma} \right)^{12} - \left(\frac{\sigma}{h + \gamma\sigma} \right)^6 \right], \quad (15)$$

where the interparticle distance r is replaced by the distance h of closest approach between the two bodies:

$$h \equiv \min(|\vec{r}_i - \vec{r}_j|) \quad \forall (i, j) \quad (16)$$

with $i \in \text{body 1}$ and $j \in \text{body 2}$. The range of interaction is controlled by an atomistic length scale $\sigma = 3.3 \text{ \AA}$, representing the effective diameter of a base pair.

In general, the calculation of h is nontrivial. We use the following approximative calculation scheme which is usually employed in connection with the GB potential:

$$h(\mathbf{A}_1, \mathbf{A}_2, \vec{r}_{12}) = r_{12} - \sigma_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}), \quad (17)$$

$$\sigma_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}) = \left[\frac{1}{2} \hat{r}_{12}^T \mathbf{G}_{12}^{-1}(\mathbf{A}_1, \mathbf{A}_2) \hat{r}_{12} \right]^{-1/2}, \quad (18)$$

$$\mathbf{G}_{12}(\mathbf{A}_1, \mathbf{A}_2) = \mathbf{A}_1^T \mathbf{S}_1^2 \mathbf{A}_1 + \mathbf{A}_2^T \mathbf{S}_2^2 \mathbf{A}_2. \quad (19)$$

In the present case of oblate objects with rather perfect stacking behavior, Eq. (17) produces only small deviations from the exact solution of Eq. (16).

The other two terms in Eq. (14) control the interaction strength as a function of the relative orientation $\mathbf{A}_1^T \mathbf{A}_2$ and position \vec{r}_{12} of interacting ellipsoids:

$$\eta_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}) = \frac{\det[\mathbf{S}_1]/\sigma_1^2 + \det[\mathbf{S}_2]/\sigma_2^2}{[\det[\mathbf{H}_{12}]/(\sigma_1 + \sigma_2)]^{1/2}}, \quad (20)$$

$$\mathbf{H}_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}) = \frac{1}{\sigma_1} \mathbf{A}_1^T \mathbf{S}_1^2 \mathbf{A}_1 + \frac{1}{\sigma_2} \mathbf{A}_2^T \mathbf{S}_2^2 \mathbf{A}_2, \quad (21)$$

$$\sigma_i(\mathbf{A}_i, \hat{r}_{12}) \equiv (\hat{r}_{12}^T \mathbf{A}_i^T \mathbf{S}_i^{-2} \mathbf{A}_i \hat{r}_{12})^{-1/2} \quad (22)$$

and

$$\chi_{12}(\mathbf{A}_1, \mathbf{A}_2, \hat{r}_{12}) = [2\hat{r}_{12}^T \mathbf{B}_{12}^{-1}(\mathbf{A}_1, \mathbf{A}_2) \hat{r}_{12}], \quad (23)$$

$$\mathbf{B}_{12}(\mathbf{A}_1, \mathbf{A}_2) = \mathbf{A}_1^T \mathbf{E}_1 \mathbf{A}_1 + \mathbf{A}_2^T \mathbf{E}_2 \mathbf{A}_2 \quad (24)$$

with

$$\mathbf{E}_i = \sigma \begin{pmatrix} \frac{a_i}{b_i c_i} & 0 & 0 \\ 0 & \frac{b_i}{a_i c_i} & 0 \\ 0 & 0 & \frac{c_i}{a_i b_i} \end{pmatrix} = \frac{\sigma}{\det[\mathbf{S}_i]} \mathbf{S}_i^2. \quad (25)$$

We neglect the electrostatic interactions between neighboring base pairs since at physiological conditions the stacking interaction dominates [18,35].

At this point, we have to find appropriate values for the thickness $2a$ and the parameter γ of Eq. (15). Both parameters influence the minimum of the GB potential. There are essentially two possible procedures. One way is to make use of the parametrization result of Everaers and Ejtehadi [36], i.e., $\gamma = 2^{1/6} - 30^{-1/6}$, and to choose a value of $a \approx 0.7$ which yields the minimum center-center distance of 3.3 \AA for perfect stacking. Unfortunately, it turns out that the fluctuations of the bending angles strongly depend on the flatness of the ellipsoids. The more flat the ellipsoids are the smaller are the fluctuations of the bending angles so that one ends up with extremely stiff filaments with a persistence length of a few thousand base pairs. This can be seen clearly for the extreme case of two perfectly stacked plates, each bending move leads then to an immediate overlap of the plates. That is why we choose the second possibility. We keep γ as a free parameter which is used in the end to shift the potential minimum to the desired value and fix the width of the ellipsoids to be approximately half the known rise value $a = 1.55 \text{ \AA}$. This requires $\gamma = 1.07$.

The sugar-phosphate backbone is known to be nearly inextensible. The distance between adjacent sugars varies from

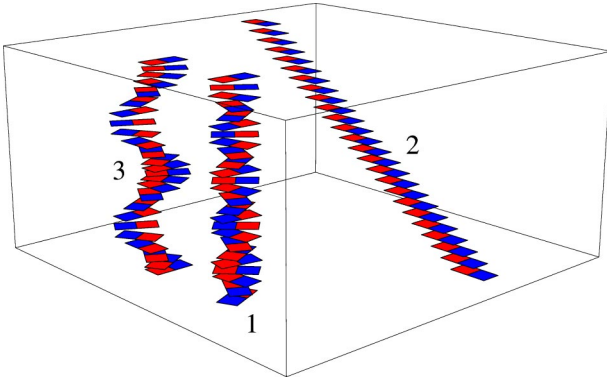


FIG. 2. (Color online) Illustration of DNA geometry for a diameter $d = 16 \text{ \AA}$: (1) Twisted ladder with $SI=Sh=0$, $Ri=3.3 \text{ \AA}$, $Tw \approx 2\pi/10$. (2) Skewed ladder with $Tw=Sh=0$, $Ri=3.4 \text{ \AA}$, $SI \approx 5.0 \text{ \AA}$. (3) Helix with $Tw=2\pi/12$, $Ri=3.4 \text{ \AA}$, $SI \approx 2.7 \text{ \AA}$, $Sh \approx 1.6 \text{ \AA}$.

5.5 \AA to 6.5 \AA [18]. This is taken into account by two stiff springs with length $l_1=l_2=6.0 \text{ \AA}$, connecting neighboring ellipsoids (see Fig. 2). The anchor points are situated along the centerline in the \vec{n} direction (compare Figs. 1 and 2) with a distance of $\pm 8 \text{ \AA}$ from the center of mass. The backbone is thus represented by an elastic spring with nonzero spring length $l_0=6 \text{ \AA}$,

$$\mathcal{H}_{el} = \frac{k}{2} [(|\mathbf{r}_{1,i+1} - \mathbf{r}_{1,i}| - l_0)^2 + (|\mathbf{r}_{2,i+1} - \mathbf{r}_{2,i}| - l_0)^2]. \quad (26)$$

Certainly a situation where the backbones are brought closer to one side of the ellipsoid so as to create a minor and a major groove would be a better description of the *B*-DNA structure. But it turns out that due to the ellipsoidal shape of the base pairs and due to the fact that the internal base-pair degrees of freedom (propeller twist, etc.) cannot relax, a non-*B*-DNA-like ground state is obtained where roll and slide motions are involved.

The competition between the GB potential that forces the ellipsoids to maximize the contact area and the harmonic springs with nonzero spring length which does not like to be compressed leads to a twist in either direction of the order of $\pm \pi/5$. The right handedness of the DNA helix is due to the excluded volume interactions between the bases and the backbone [18], which we do not represent explicitly. Rather we break the symmetry by rejecting the moves which lead to local twist smaller than $-\pi/18$.

Thus we are left with three free parameters in our model: the GB energy depth $\epsilon = \min(U)$ which controls the stacking interaction, the spring constant k which controls the torsional rigidity, and the depth b of the ellipsoids which influences mainly the fluctuations of the bending angles. All other parameters such as the width and the height of the ellipsoids or the range of interaction $\sigma = 3.3 \text{ \AA}$, which determines the width of the GB potential, are fixed so as to reproduce the experimental values for *B*-DNA.

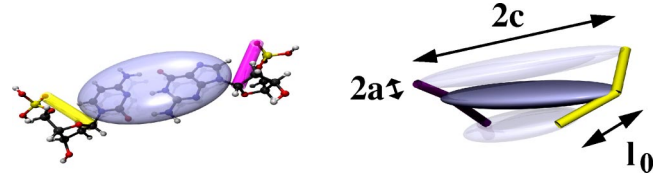


FIG. 3. (Color online) (left) Illustration of the underlying idea. The base pairs are represented as rigid ellipsoids. The sugar-phosphate backbone is treated as semirigid springs connecting the edges of the ellipsoid. (right) Introduced interactions lead to a right-handed twisted structure.

B. MC simulation

In our model, all interactions are local and it can therefore conveniently be studied using a MC scheme. In addition to trial moves, consisting of local displacements and rotations of one ellipsoid by a small amplitude, it is possible to employ global moves which modify the position and the orientation of large parts of the chain. The moves are analogous to (i) the well-known pivot move [40] and (ii) a crankshaft move where two randomly chosen points along the chain define the axis of rotation around which the inner part of the chain is rotated. The moves are accepted or rejected according to the Metropolis scheme [41].

Figure 3 shows that these global moves significantly improve the efficiency of the simulation. We measured the correlation time τ of the scalar product of the tangent vectors of the first and the last monomer of 200 independent simulation runs with $N=10, 20, 50$ monomers using (i) only local moves and (ii) local and global moves (ratio 1:1). The correlation time of the global moves is independent of the chain length with $\tau_{global} \approx 78$ sweeps, whereas τ_{local} scales as N^3 .

Each simulation run comprises 10^6 MC sweeps where one MC sweep corresponds to $2N$ trials (one rotational and one translational move per base pair) with N denoting the number of monomers. The amplitude is chosen such that the acceptance rate equals approximately 50%. After every 1000 sweeps, we store a snapshot of the DNA conformation. We measured the “time” correlation functions of the end-to-end distance, the rise of one base pair inside the chain, and all three orientational angles of the first and the last monomer and of two neighboring monomers inside the chain in order to extract the longest relaxation time τ_{max} . We observe $\tau_{max} < 1000$ for all simulation runs.

An estimate for the central processing unit (CPU) time required for one sweep for chains of length $N=100$ on a AMD Athlon MP 2000+ processor results in 0.026 s, which is equivalent to 1.33×10^{-4} s per move.

C. Energy minimization

We complemented the simulation study by zero temperature considerations that help to discuss the geometric structure, obtained by the introduced interactions, and to rationalize the MC simulation data. Furthermore, they can be used to obtain an estimate of the critical force f_{crit} that must be applied to enable the structural transition from *B*-DNA to the overstretched *S*-DNA configuration as a function of the model parameters $\{\epsilon, k, b\}$.

IV. RESULTS

In the following, we will try to motivate an appropriate parameter set $\{\epsilon, k, b\}$ that can be used for further investigations within the framework of the presented model. Therefore we explore the parameter dependence of experimental observables such as the bending persistence length of *B*-DNA, $l_p \approx 150$ bp, the torsional persistence length $l_t \approx 260$ bp [42], the mean values and correlations of all six base-pair parameters and the critical pulling force $f_{crit} \approx 65$ pN [11,43–45] which must be applied to enable the structural transition from *B*-DNA to the overstretched *S*-DNA configuration. In fact, static and dynamic contributions to the bending persistence length l_p of DNA are still under discussion. It is known that l_p depends on both the intrinsic curvature of the double helix due to spontaneous bending of particular base-pair sequences and the thermal fluctuations of the bending angles. Bensimon *et al.* [46] introduced disorder into the WLC model by an additional set of preferred random orientation between successive segments, and found the following relationship between the pure persistence length l_{pure} , i.e. without disorder, the effective persistence length l_{eff} , and the persistence length $l_{disorder}$ caused by disorder:

$$\frac{l_{eff}}{l_{pure}} = \begin{cases} 1 - \frac{\sqrt{l_{pure}}}{2l_{disorder}}, & \frac{l_{pure}}{l_{disorder}} \ll 1 \\ \frac{2}{l_{pure}}, & \frac{l_{pure}}{l_{disorder}} \gg 1. \end{cases} \quad (27)$$

Since we are dealing with intrinsically straight filaments with $1/l_{disorder} = 0$, we measure l_{pure} . The recent estimates of $l_{disorder}$ range between 430 [47] and 4800 [48] bp using cryoelectron microscopy and cyclization experiments, respectively, implicating values between 105 and 140 bp for l_{pure} .

A. Equilibrium structure

As a first step, we study the equilibrium structure of our chains as a function of the model parameters. To investigate the ground state conformation, we rationalize the MC simulation results with the help of the geometrical considerations and minimum energy calculations. In the end, we will choose parameters for which our model reproduces the experimental values of *B*-DNA [18]:

$$\begin{aligned} \langle Ri \rangle &= 3.3 - 3.4 \text{ \AA}, \\ \langle Sl \rangle &= 0 \text{ \AA}, \\ \langle Sh \rangle &= 0 \text{ \AA}, \\ \langle Tw \rangle &= 2\pi/10.5 - 2\pi/10, \\ \langle Ti \rangle &= 0, \end{aligned}$$

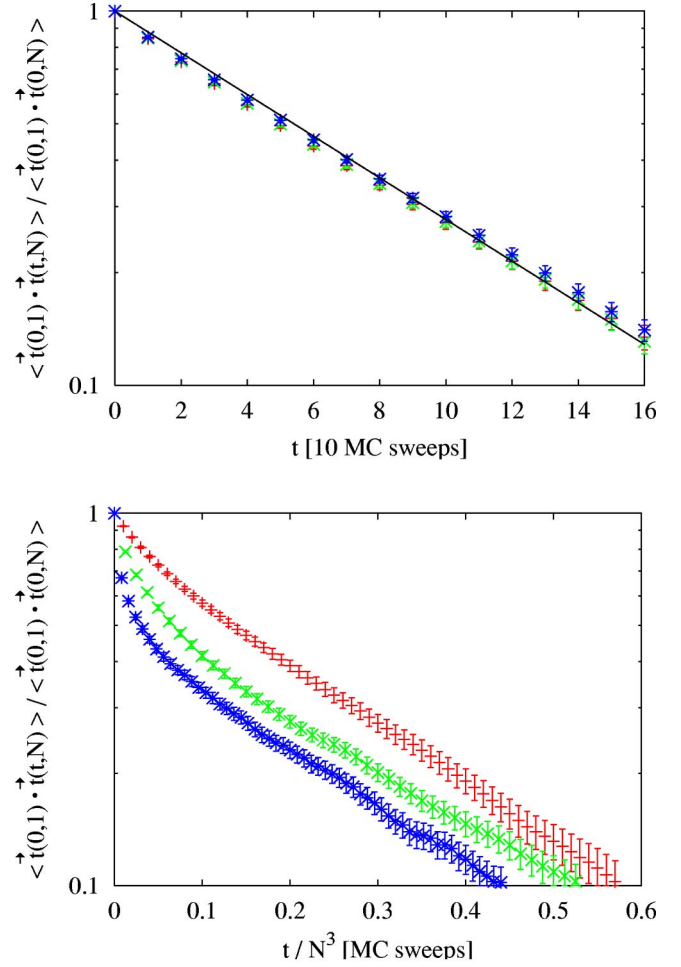


FIG. 4. (Color online) Time correlation functions of the scalar product of the tangent vectors of the first and the last monomer, $\tau = \vec{t}(0,1) \cdot \vec{t}(t,N)$ with $N=10$ (red, plus), $N=20$ (green, crosses), $N=50$ (blue, stars) for (a) global and (b) local moves. It is observed that τ_{global} is independent of the chain length N , whereas τ_{local} scales as N^3 . The “time” is measured in units of sweeps where one MC sweep corresponds to N trials. The CPU time for one sweep scales as N^2 in case of global moves and as N in case of local moves. Thus the simulation time t scales as $t_{local} \propto N^4$ and $t_{global} \propto N^2$.

$$\langle Ro \rangle = 0.$$

We use the following reduced units in our calculations. The energy is measured in the units of $k_B T$, lengths in the units of \AA , forces in the units of $k_B T \text{\AA}^{-1} \approx 40$ pN.

We start by minimizing the energy for the various conformations shown in Fig. 4 to verify that our model Hamiltonian indeed prefers the *B* form. Since we have only local (nearest-neighbor) interactions, we can restrict the calculations to two base pairs. There are three local minima which have to be considered: (i) a stacked-twisted conformation with $Ri=3.3$, Sl , Sh , Ti , $Ro=0$, $Tw=\pi/10$, (ii) a skewed ladder with $Ri=3.3$, $Sl=5.0$, Sh , Tw , Ti , $Ro=0$, and (iii) an unwound helix with $Ri=6.0$, Sl , Sh , Ti , $Ro=0$, $Tw=0$.

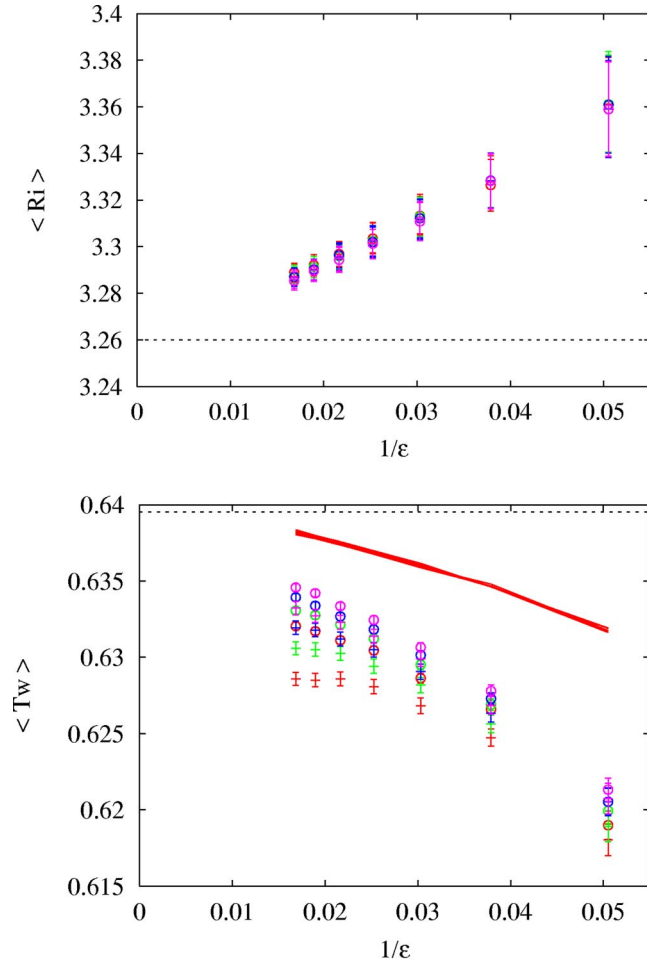


FIG. 5. (Color online) (a) Rise (\AA) and (b) twist as a function of $\epsilon [k_B T]$ for $2b=8, 9, 10, 11 \text{ \AA}$ (red, green, blue, purple). For each b , there are two data sets for $k=32$ (plus), 64 (circles) [$k_B T/\text{\AA}^2$]. The dotted line corresponds to the minimum energy value. $\langle Ri \rangle$ depends only on ϵ . In the limit of $\epsilon \rightarrow \infty$, the minimum energy value is reached. (b) In addition to the MC data and the minimum energy calculation, we calculated the twist with Eq. (1) using the measured mean rise values of (a) (red solid lines). One can observe that $\langle Tw \rangle$ changes with all three model parameters. Increasing y and k decreases especially the fluctuations of Tw and Sh so that $\langle Tw \rangle$ increases as a result of the mechanical coupling of the shift and twist motions. In the limit of $\epsilon, k \rightarrow \infty$, the minimum energy value is reached.

Without an external pulling force the global minimum is found to be the stacked-twisted conformation.

We investigated the dependence of Ri and Tw on the GB energy depth ϵ that controls the stacking energy for different spring constants k . Ri depends neither on ϵ , nor on k , and nor on b . It shows a constant value of $Ri \approx 3.3 \text{ \AA}$ for all parameter sets $\{\epsilon, k, b\}$. The resulting Tw of the minimum energy calculation coincides with the geometrically determined value under the assumption of fixed Ri up to a critical ϵ . Up to that value the springs behave effectively as rigid rods. The critical ϵ is determined by the torque $\tau(k, \epsilon)$ that has to be applied to open the twisted structure for a given value of Ri .

Using MC simulations, we can study the effects arising from the thermal fluctuations. Plotting $\langle Ri \rangle$ and $\langle Tw \rangle$ as a

TABLE I. Dependence of mean values of all six step parameters and of the mean center-center distance $\langle c \rangle$ on the temperature for $2b=11 \text{ \AA}$, $\epsilon=20k_B T$, $k=64k_B T/\text{\AA}^2$. $\langle Ri \rangle$, $\langle Sh \rangle$, $\langle Sl \rangle$, and $\langle c \rangle$ are measured in \AA , l_p in base pairs.

T	$\langle Ri \rangle$	$\langle Sh \rangle$	$\langle Sl \rangle$	$\langle Tw \rangle$	$\langle Ti \rangle$	$\langle Ro \rangle$	$\langle c \rangle$	l_p
0	3.26	0.0	0.0	0.64	0.0	0.0	3.26	∞
1	3.37	0.01	-0.01	0.62	0.0	0.0	3.47	172.8
2	3.76	-0.01	-0.03	0.47	0.0	0.0	4.41	25.3
3	4.10	-0.01	0.01	0.34	0.0	-0.01	5.07	14.4
5	4.30	0.03	-0.02	0.27	0.0	0.01	5.39	13.6

function of the GB energy depth ϵ , one recognizes that in general $\langle Ri \rangle$ is larger than $Ri(T=0)$. It converges only for large values of ϵ to the minimum energy values. This can be understood as follows. Without fluctuations the two base pairs are perfectly stacked taking the minimum energy configuration $Ri=3.3 \text{ \AA}$, $Sl, Sh, Ti, Ro=0$, and $Tw=\pi/10$. As the temperature is increased the fluctuations can only occur to larger Ri values due to the repulsion of neighboring base pairs. A decrease of Ri would cause the base pairs to intersect. Increasing the stacking energy reduces the fluctuations in the direction of the tangent vector and leads to smaller $\langle Ri \rangle$ value. In the limit $\epsilon \rightarrow \infty$, it should reach the minimum energy value which is observed from the simulation data. In turn the increase of the mean value of rise results in a smaller twist angle $\langle Tw \rangle$. We can calculate with the help of Eq. (1) the expected twist using the measured mean values of $\langle Ri \rangle$. Figure 5 shows that there is no agreement. The deviations are due to the fluctuations in Sl and Sh which cause the base pairs to untwist. This is the mechanical coupling of Sl, Sh , and Tw due to the backbones already mentioned in Sec. II A. It is observed that a stiffer spring k and a larger depth b of the ellipsoids result in larger mean twist values. Increasing the spring constant k means decreasing the fluctuations of the twist and, due to the mechanical coupling, of the shift motion around the mean values which explains the larger mean twist values. An increase of the ellipsoidal depth b in turn decreases the fluctuations of the bending angles. The coupling of the tilt fluctuations with the shift fluctuations leads to larger values for $\langle Tw \rangle$. The corresponding limit where $\langle Tw \rangle \rightarrow Tw(T=0)$ is given by $k, \epsilon \rightarrow \infty$.

The measurement of the mean values of all six base-pair step parameters for different temperatures is shown in Table I. One can see that with increasing the temperature, the twist angles decrease while the mean value of rise increases. The increase of the center-center distance is not only due to fluctuations in Ri but also due to fluctuations in Sl and Sh . That is why there are strong deviations of $\langle c \rangle$ from $\langle Ri \rangle$ even though the mean values of Sl and Sh vanish. Note that the mean backbone length $\langle l \rangle$ always amounts to about 6 \AA .

The calculation of the probability distribution functions of all six base-pair parameters shows that especially the rise and twist motions do not follow a Gaussian behavior (Fig. 7). The deviation of the distribution functions from the Gaussian shape depends mainly on the stacking energy determined by ϵ . For smaller values of ϵ , one observes larger deviations than for large ϵ values.

It is worthwhile to mention that there are mainly two correlations between the base-pair parameters. The first is a microscopic twist-stretch coupling determined by a correlation of R_i and Tw , i.e., an untwisting of the helix implicates larger rise values. A twist-stretch coupling was introduced in earlier rod models [49–51], motivated by experiments with torsionally constrained DNA [52] which allow for the determination of this constant. Here it is the result of the preferred stacking of neighboring base pairs and the rigid backbones. The second correlation is due to the constrained tilt motion. If we return to our geometrical ladder model, we recognize immediately that a tilt motion alone will always violate the constraint of fixed backbone length l . Even though we allow for backbone fluctuations in the simulation, the bonds are very rigid which makes tilting energetically unfavorable. To circumvent this constraint, tilting always involves a directed shift motion.

Figure 6 shows that we recover the anisotropy of the bending angles Ro and Ti as a result of the spatial dimensions of the ellipsoids. Since the overlap of the successive ellipsoids is larger in case of rolling, it is more favorable to roll than to tilt.

The correlations can be quantified by calculating the correlation matrix C of Eq. (6). Inverting C yields the effective coupling constants of the SOP model, $\mathcal{K}=C^{-1}$. Due to the local interactions, it suffices to calculate the mean and mean-squared values of R_i , Sl , Sh , Tw , Ro , and Ti , characterizing the “internal” couplings of the base pairs:

$$C = (\sigma)_{ij} \quad \forall i, j \in \{1, \dots, 6\}, \quad (28)$$

with $\sigma_{x,y} = \langle xy \rangle - \langle x \rangle \langle y \rangle$.

B. Bending and torsional rigidity

The correlation matrix of Eq. (28) can also be used to check Eqs. (8) and (11). Therefore we measured the orientational correlation functions $\langle \mathbf{t}_i \cdot \mathbf{t}_j \rangle$, $\langle \mathbf{n}_i \cdot \mathbf{n}_j \rangle$, $\langle \mathbf{b}_i \cdot \mathbf{b}_j \rangle$ and compared the results to the analytical expressions as it is illustrated in Fig. 8. The agreement is excellent.

The simulation data show that the bending persistence length does not depend on the spring constant k . But it strongly depends on ϵ being responsible for the energy that must be paid to tilt or roll two respective base pairs. Since a change of twist for constant R_i is proportional to a change in bond length, the bond energy contributes to the twist persistence length explaining the dependence of l_{Tw} on k (compare Fig. 9).

We also measured the mean-square end-to-end distance $\langle R_E^2 \rangle$ and find that $\langle R_E^2 \rangle$ deviates from the usual WLC chain result due to the compressibility of the chain. So as to investigate the origin of the compressibility, we calculate $\langle R_E^2 \rangle$ for the following geometry. We consider two base pairs without spontaneous bending angles such that the end-to-end vector \vec{R}_E can be expressed as

$$\vec{R}_E = \sum_i \vec{c}_i = \sum_i (R_i \mathbf{t}_i + Sh \mathbf{b}_i + Sl \mathbf{n}_i). \quad (29)$$

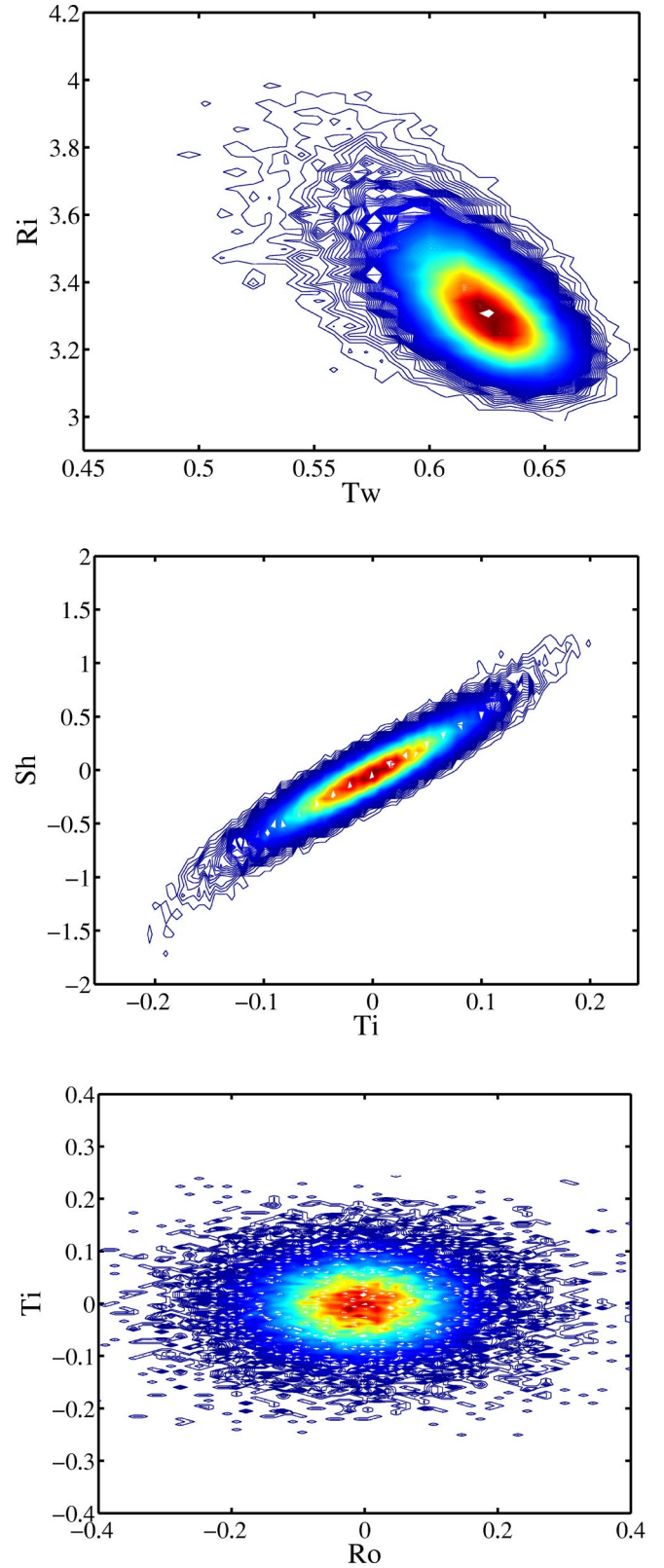


FIG. 6. (Color online) Contour plots of the measured clouds for rise-twist, shift-tilt, and roll-tilt to demonstrate the internal couplings and the anisotropy of the bending angles ($2b=11 \text{ \AA}$, $\epsilon=20k_B T$, $k=64k_B T/\text{\AA}^2$).

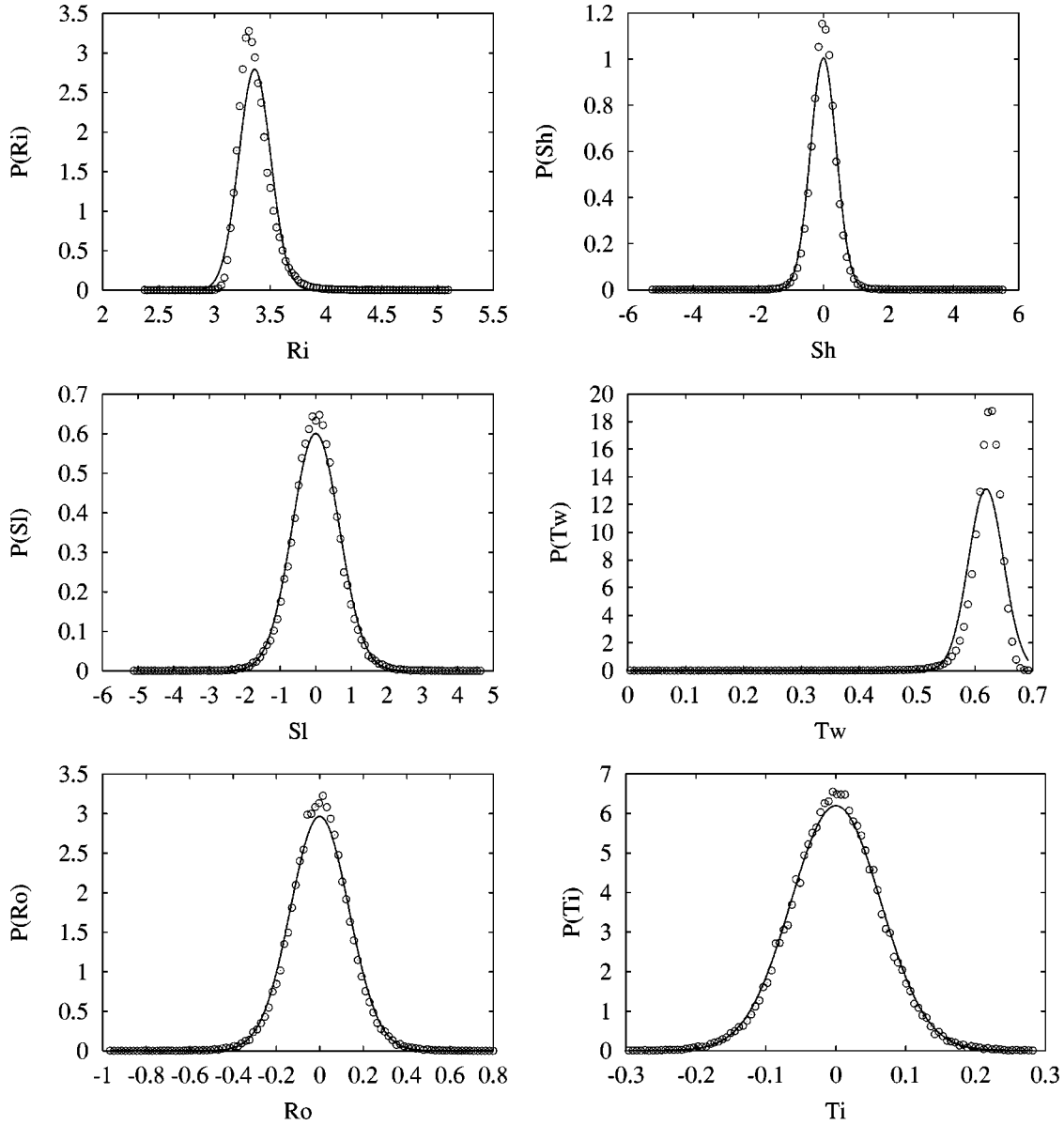


FIG. 7. Comparison of the probability distribution functions of all base-pair parameters for $\epsilon=20k_B T$, $k=64k_B T/\text{\AA}^2$, $2b=8 \text{\AA}$. The Gaussians (black solid line) are plotted with the measured mean and mean-squared values of the MC simulation, and are in good agreement with the simulation data (circles) except for Ri and Tw.

The coordinate system $\{\mathbf{t}_i, \mathbf{b}_i, \mathbf{n}_i\}$ is illustrated in Fig. 1. \vec{c}_i denotes the center-center distance of two neighboring base pairs. Since successive base-pair step parameters are independent of each other and Ri, Sh, and Sl are uncorrelated, the mean-square end-to-end distance $\langle R_E^2 \rangle$ is given by

$$\begin{aligned} \langle R_E^2 \rangle &= \sum_i (\langle c_i^2 \rangle - \langle \text{Ri} \rangle^2) + \sum_i \sum_j \langle \text{Ri} \rangle^2 \langle \mathbf{t}_i \cdot \mathbf{t}_j \rangle \\ &= \frac{N \langle \text{Ri} \rangle}{\gamma} + 2N \langle \text{Ri} \rangle l_p - 2l_p^2 \left[1 - \exp\left(-\frac{N \langle \text{Ri} \rangle}{l_p}\right) \right], \end{aligned} \quad (30)$$

where N denotes the number of base pairs. Note that $\langle \text{Sl} \rangle$ and

$\langle \text{Sh} \rangle$ vanish. Using $\langle c_i^2 \rangle = \langle \text{Ri}^2 \rangle + \langle \text{Sh}^2 \rangle + \langle \text{Sl}^2 \rangle$, the stretching modulus γ is simply given by

$$\gamma = \frac{\langle \text{Ri} \rangle}{(\langle \text{Ri}^2 \rangle - \langle \text{Ri} \rangle^2) + \langle \text{Sh}^2 \rangle + \langle \text{Sl}^2 \rangle}. \quad (31)$$

We compared the data for different temperatures T to Eq. (30) using the measured bending persistence lengths l_p and stretching moduli γ (see Fig. 10). The agreement is excellent. This indicates that *transverse* slide and shift fluctuations contribute to the *longitudinal* stretching modulus of the chain.

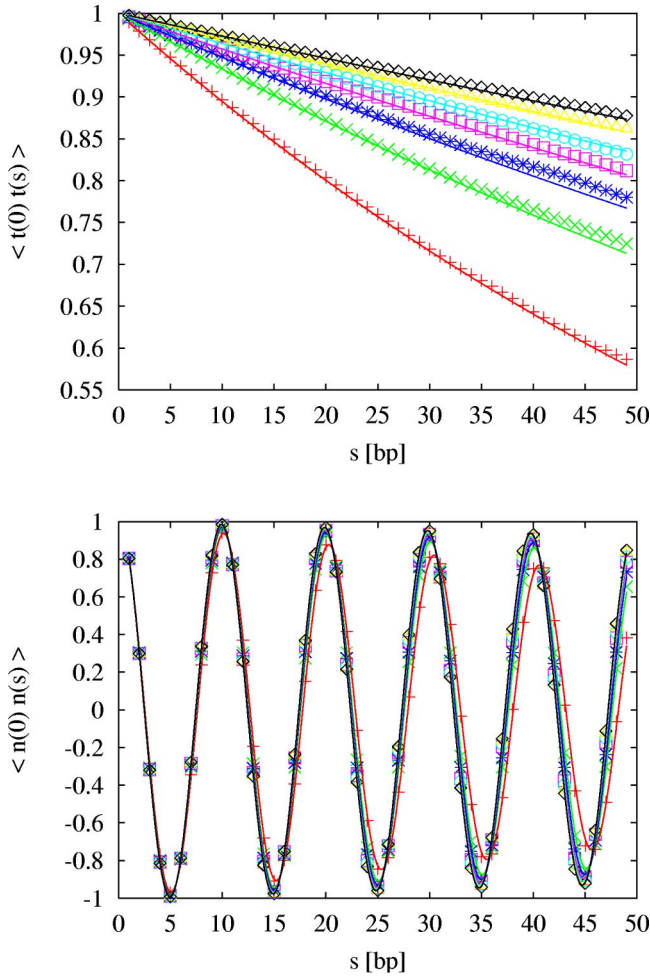


FIG. 8. (Color online) Comparison of the analytical expressions [Eqs. (8) and (11)] for l_p and l_n (solid lines) with numerically calculated orientational correlation functions (data points) for $2b = 8 \text{ \AA}$, $k = 64k_B T/\text{\AA}^2$, and $\epsilon = 20, \dots, 60 [k_B T]$ (red, plus; ...; black, diamonds).

C. Stretching

The extension experiments on the double-stranded *B*-DNA have shown that the overstretching transition occurs when the molecule is subjected to stretching forces of 65 pN or more [45]. The DNA molecule thereby increases in length by a factor of 1.8 times the normal contour length. This overstretched DNA conformation is called *S*-DNA. The structure of *S*-DNA is still under discussion. First evidence of the possible *S*-DNA conformations were provided by Lavery *et al.* [11,43,44] using atomistic computer simulations.

In principle, one can imagine two possible scenarios how the transition from *B*-DNA to *S*-DNA occurs within our model. Either the chain untwists and unstacks resulting in an untwisted ladder with approximately 1.8 times the equilibrium length, or the chain untwists and the base pairs slide against each other resulting in a skewed ladder with the same *S*-DNA length. The second scenario should be energetically favorable since it provides a possibility to partially conserve the stacking of successive base pairs. In fact, molecular modeling of the DNA stretching process [11,43,44] yielded both

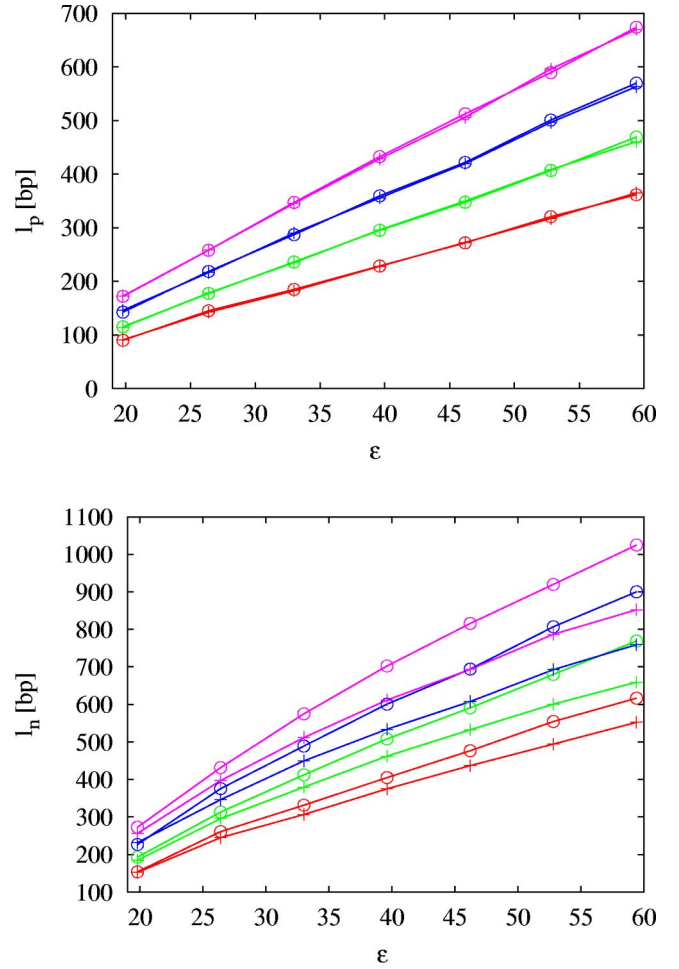


FIG. 9. (Color online) Dependency of (a) bending persistence length l_p and (b) torsional persistence length l_n on the spring constant k , the width of the ellipsoids b , and the energy depth ϵ . We measured the persistence lengths for varying width sizes $2b = 8, 9, 10, 11 \text{ \AA}$ (red, green, blue, purple; from bottom to top) and for two different spring constants $k = 32$ (plus), 64 (circles) [$k_B T/\text{\AA}^2$]. The bending persistence length depends solely on b and ϵ . It gets larger for larger ϵ and b values. But it does not depend on k (the curves for different k values corresponding to the same width b lie one upon the other). The torsional persistence length in turn depends on k , since a change of twist for constant Ri is proportional to a change in bond length.

a conformation with strong inclination of base pairs and an unwound ribbon depending on which strand one pulls.

We expect that the critical force f_{crit} where the structural transition from *B*-DNA to overstretched *S*-DNA occurs depends only on the GB energy depth ϵ , controlling the stacking energy. So as a first step to find an appropriate value of ϵ as input parameter for the MC simulation, we minimize the Hamiltonian with an additional stretching energy $E_{pull} = f c_{i,i+1}$, where the stretching force acts along the center-of-mass axis, with respect to Ri , SI , and Tw for a given pulling force f . Figure 11 shows the resulting stress-strain curve. First, the pulling force acts solely against the stacking energy up to the critical force where a jump from $L(f_{crit-})/L_0 \approx 1.05$ to $L(f_{crit+})/L_0 = \sqrt{Ri^2 + SI^2}/Ri \approx 1.8$ oc-

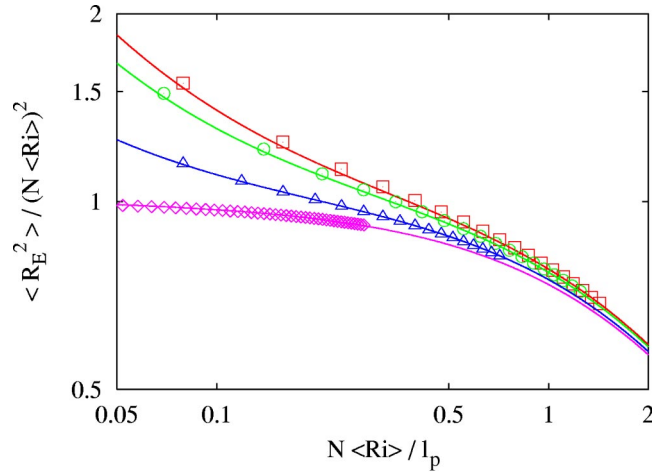


FIG. 10. (Color online) Comparison of the simulation data with $\epsilon=20k_B T$, $k=64k_B T/\text{\AA}^2$, $2b=11 \text{\AA}$, and $T=1$ (purple, diamonds), 2 (blue, triangles), 3 (green, circles), 5 (red, squares) to Eqs. (8), (30), and (31) (solid lines). Using the measured bending persistence lengths and the stretching moduli, we find a good agreement with the predicted behavior. For $T=1$, we obtain $\gamma=6.02 \text{\AA}^{-1}$.

curs, followed by another slow increase of the length caused by the overstretching the bonds. $L_0=L(F=0)=Ri$ denotes the stress-free center-of-mass distance. As already mentioned, three local minima are obtained: (i) a stacked-twisted conformation, (ii) a skewed ladder, and (iii) an unwound helix. The strength of the applied stretching force determines which of the local minima becomes the global one. The global minimum for small stretching forces is determined to be the stacked-twisted conformation and the global minima for stretching forces larger than f_{crit} is found to be the skewed ladder. Therefore the broadness of the force plateau depends solely on the ratio of l/Ri determined by the geometry of the base pairs S and the bond length $l=6.0 \text{\AA}$. A linear relationship is obtained between the critical force and the stacking energy ϵ so that one can extrapolate to smaller ϵ values in order to extract the ϵ value that reproduces the experimental value of $f_{crit} \approx 65 \text{ pN}$. This suggests a value of $\epsilon \approx 7$.

The simulation results of the previous sections show several problems when this value of ϵ is chosen. First of all, it cannot produce the correct persistence lengths as the chain is far too flexible. Second, the undistorted ground state is not a B -DNA anymore. The thermal fluctuations suffice to unstack and untwist the chain locally. That is why one has to choose larger ϵ values even though the critical force is going to be overestimated.

Therefore we choose the following way to fix the parameter set $\{b, \epsilon, k\}$. First of all, we choose a value for the stacking energy that reproduces correctly the persistence length. Afterwards the torsional persistence length is fixed to the experimentally known values by choosing an appropriate spring constant k . The depth of the base pairs has also an influence on the persistence lengths of the chain. If the depth b is decreased, larger fluctuations for all the three rotational parameters are gained such that the persistence lengths get smaller. Furthermore, the geometric structure and the behav-

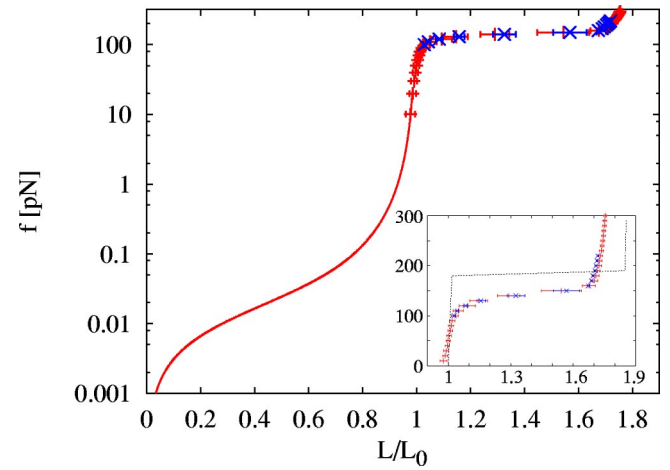


FIG. 11. (Color online) Force-extension relation calculated by the minimum energy calculation (black) and obtained by MC simulation for 50 (red, plus) and 500 (blue, crosses) bp. The red solid line represents the analytical result of the WLC. Inset: The deviation between energy minimization (black dotted line) and MC in the critical force is due to the entropic contributions.

ior under pulling is very sensitive to b . Very small values provoke non- B -DNA conformations or unphysical S -DNA conformations. We choose for b a value of 11\AA for those reasons. For $\epsilon=20$ and $k=64$, a bending stiffness of $l_p=170 \text{ bp}$ and a torsional stiffness of $l_n=270 \text{ bp}$ are obtained close to the experimental values. We use this parameter set to simulate the corresponding stress-strain relation.

The simulated stress-strain curves for 50 bp show the following three different regimes (see Fig. 11).

(a) For small stretching forces, the WLC behavior of the DNA, in addition with the linear stretching elasticity of the backbones is recovered. This regime is completely determined by the chain length N . Due to the coarse-graining procedure that provides analytic expressions of the persistence lengths depending on the base-pair parameters [see Eqs. (8) and (11)], it is not necessary to simulate a chain of a few thousand base pairs. The stress-strain relation of the entropic and WLC stretching regime (small relative extensions L/L_0 and small forces) is known analytically [20,53]. Since we have parametrized the model in such a way that we recover the elastic properties of DNA on large length scales, the simulation data for very long chains will follow the analytical result for small stretching forces.

(b) Around the critical force $f_{crit} \approx 140 \text{ pN}$, which is mainly determined by the stacking energy of the base pairs, the structural transition from B -DNA to S -DNA occurs.

(c) For larger forces the bonds become overstretching. Our MC simulations suggest a critical force $f_{crit} \approx 140 \text{ pN}$ which is slightly smaller than the value $f_{crit} \approx 180 \text{ pN}$ calculated by minimizing the energy. This is due to entropic contributions.

In order to further characterize the B -to- S transition, we measured the mean values of rise, slide, shift, etc., as a function of the applied forces. The evaluation of the MC data shows that the mean values of shift, roll, and tilt are completely independent of the applied stretching force and they vanish for all f . Rise increases at the critical force from the

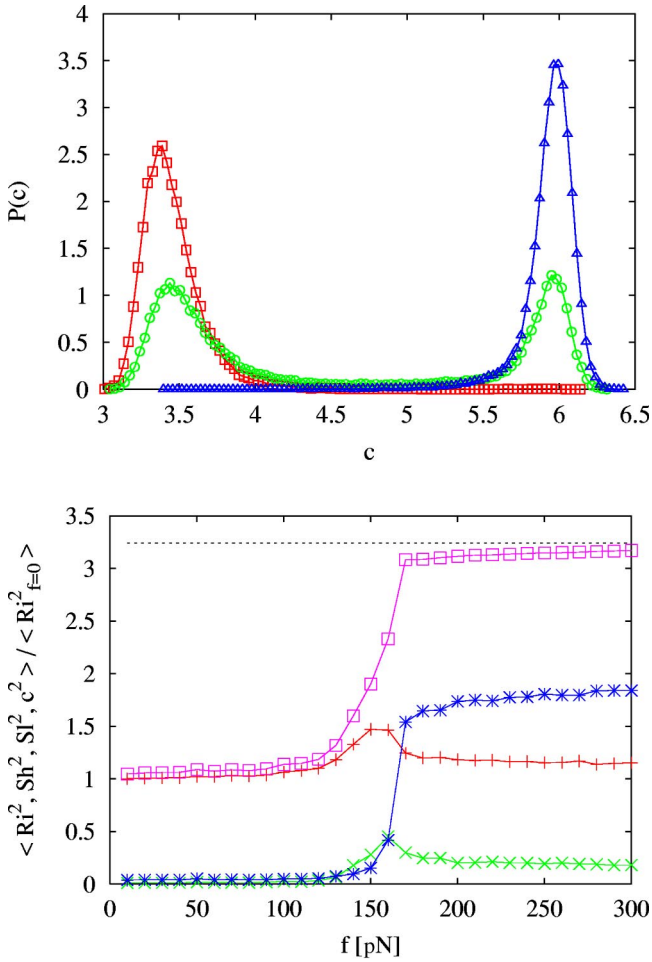


FIG. 12. (Color online) (a) Probability distribution function of the center-center distance of successive base pairs for $f=0$ (red, squares), 140 (green, spheres), 200 pN (blue, triangles). (b) Mean-squared values of rise (red, plus), shift (green, crosses), slide (blue, stars), and center-of-mass distance (purple, squares) for neighboring base pairs as a function of the stretching force f . The dashed line corresponds to the S -DNA center-of-mass distance. $\langle Tw \rangle$ of the resulting S -DNA conformation vanishes as predicted by Eq. (3).

undisturbed value of 3.3 \AA to approximately 4.0 \AA and decays subsequently to the undisturbed value. Quite interestingly, the mean value of slide jumps from its undisturbed value of 0 to $\pm 5 \text{ \AA}$ (no direction is favored) and the twist changes at the critical force from $\pi/10$ to 0. The calculation of the distribution function of the center-center distance c of two neighboring base pairs for $f=140$ pN yields a double-peaked distribution (see Fig. 12), indicating that a part of the chain is in the B form and a part of the chain in the S form. The contribution of the three translational degrees of freedom to the center-center distance c is shown in Fig. 12. The S -DNA conformation is characterized by $Ri=3.3 \text{ \AA}$, $SI = \pm 5 \text{ \AA}$, and $Tw=0$ (Fig. 13). In agreement with Refs. [11,43], we obtain a conformation with highly inclined base pairs still allowing for partial stacking of successive base pairs.

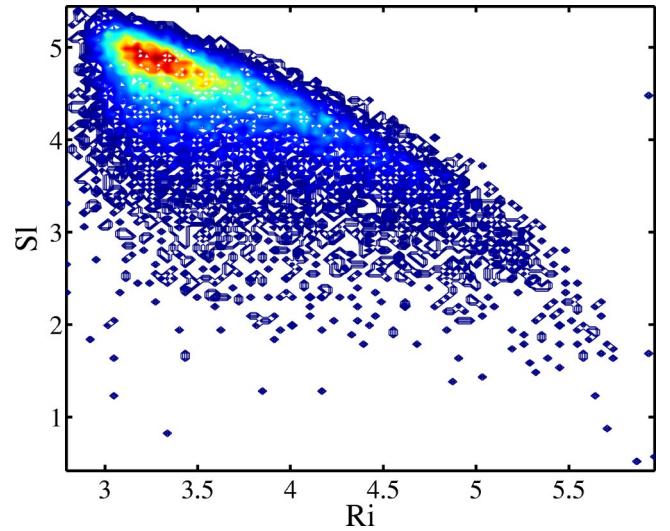


FIG. 13. (Color online) Contour plot of rise (\AA) versus slide (\AA) for the S -DNA conformation.

V. DISCUSSION

We have proposed a simple model Hamiltonian describing the double-stranded DNA on the base-pair level. Due to the simplification of the force field and, in particular, the possibility of nonlocal MC moves, our model provides access to much larger length scales than atomistic simulations. For example, $4h$ on a AMD Athlon MP 2000+ processor are sufficient in order to generate 1000 independent conformations for chains consisting of $N=100$ bp.

In the data analysis, the main emphasis was on deriving the elastic constants on the elastic rod level from the analysis of the thermal fluctuations of base-pair step parameters. Assuming a twisted ladder as the ground state conformation, one can provide an analytical relationship between the persistence lengths and the local elastic constants given by Eqs. (8) and (11) [66]. Future work has to show, if it is possible to obtain suitable parameters for our mesoscopic model from a corresponding analysis of atomistic simulations [54] or quantum-chemical calculations [55]. In the present paper, we have chosen a top-down approach, i.e., we try to reproduce the experimentally measured behavior of DNA on length scales *beyond* the base diameter. The analysis of the persistence lengths, the mean and mean-squared values of all six base-pair parameters, and the critical force, where the structural transition from B -DNA to S -DNA takes place, as a function of the model parameters $\{b, k, \epsilon\}$ and the applied stretching force f suggests the following parameter set:

$$2b = 11 \text{ \AA}, \quad (32)$$

$$\epsilon = 20k_B T, \quad (33)$$

$$k = 64k_B T / \text{\AA}^2. \quad (34)$$

It reproduces the correct persistence lengths for *B*-DNA and entails the correct mean values of the base-pair step parameters known by the x-ray-diffraction studies. While the present model does not include the distinction between the minor and major grooves and suppresses all internal degrees of freedom of the base pairs such as propeller twist, it nevertheless reproduces some experimentally observed features on the base-pair level. For example, the anisotropy of the bending angles (rolling is easier than tilting) is just a consequence of the platelike shape of the base pairs and the twist-stretch coupling is the result of the preferred stacking of the neighboring base pairs and the rigid backbones.

The measured critical force is overestimated by a factor of 2 and cannot be improved further by fine tuning of the three free model parameters $\{b, k, \epsilon\}$. f_{crit} depends solely on the stacking energy value ϵ that cannot be reduced further. Otherwise neither the correct equilibrium structure of *B*-DNA nor the correct persistence lengths would be reproduced. Our model suggests a structure for *S*-DNA with highly inclined base pairs so as to enable at least partial base-pair stacking. This is in good agreement with the results of atomistic *B*-DNA simulations by Lavery and co-workers [11,43]. They found a force plateau of 140 pN for freely rotating ends [11]. The mapping to the SOP model yields the following twist-stretch (Ri-Tw) coupling constant: $k_{Ri,Tw} = (C^{-1})_{Ri,Tw} = 267/\text{\AA}$. $k_{Ri,Tw}$ is the microscopic coupling of rise and twist describing the untwisting of the chain due to an increase of rise (compare also Fig. 6).

The possible applications of the present model include the investigation of (i) the charge renormalization of the WLC elastic constants [56], (ii) the microscopic origins of the cooperativity of the *B*-to-*S* transition [57], and (iii) the influence of nicks in the sugar-phosphate backbone on force-elongation curves. In particular, our model provides a physically sensible framework to study the intercalation of certain drugs or of ethidium bromide between base pairs. The latter is a hydrophobic molecule of roughly the same size as the base pairs that fluoresces green and likes to slip between two base pairs forming an DNA-ethidium-bromide complex. The fluorescence properties allow to measure the persistence lengths of DNA [6]. It was also used to argue that the force plateau is the result of a DNA conformational transition [11].

In the future, we plan to generalize our approach to a description on the base level, which includes the possibility of hydrogen-bond breaking between complementary bases along the lines of Refs. [30,31]. A suitably parametrized model allows a more detailed investigation of DNA unzipping experiments [58] as well as a direct comparison between the two mechanism currently discussed for the *B*-to-*S* transition: the formation of skewed ladder conformations (as in the present paper) versus local denaturation [59–61]. Clearly, it is possible to study the sequence effects and even more refined models of DNA. For example, it is possible to mimic the minor and major grooves by bringing the backbones closer to one side of the ellipsoids without observing the non-*B*-DNA-like ground states. The relaxation of the internal degrees of freedom of the base pairs, characterized by another set of parameters (propeller twist, stagger, etc.), should help to reduce the artifacts which are due to the el-

lipsoidal shape of the base pairs. Sequence effects enter via the strength of the hydrogen bonds ($E_{GC} = 2.9k_B T$ versus $E_{AT} = 1.3k_B T$) as well as via base-dependent stacking interactions [35]. For example, one finds for guanine a concentration of negative charge on the major-groove edge, whereas for cytosine one finds a concentration of positive charge on the major-groove edge. For adenine and thymine instead there is no strong joint concentration of partial charges [18]. It is known that in a solution of water and ethanol, where the hydrophobic effect is less dominant, these partial charges cause GG/CC steps to adopt *A* or *C* forms [62] by a negative slide and positive roll motion and a positive slide motion, respectively. Thus by varying the ratio of the strengths of the stacking versus the electrostatic energy, it should be possible to study the transition from *B*-DNA to *A*-DNA and *C*-DNA, respectively.

VI. SUMMARY

Inspired by the results of Hassan and Calladine [33] and of Hunter and co-workers [34,35], we have put forward the idea of constructing simplified DNA models on the base(-pair) level where discotic ellipsoids (whose stacking interactions are modeled via coarse-grained potentials [36,37]) are linked to each other in such a way as to preserve the DNA geometry, its major mechanical degrees of freedom, and the physical driving forces for the structure formation [18].

In the present paper, we have used energy minimization and Monte Carlo simulations to study a simple representative of this class of DNA models with nonseparable base pairs. For a suitable choice of parameters, we obtained a *B*-DNA-like ground state as well as realistic values for the bend and twist persistence lengths. The latter were obtained by analyzing the thermal fluctuations of long filaments as well as by a systematic coarse-graining from the stack-of-plates to the elastic rod level. In studying the response of DNA to external forces or torques, models of the present type are not restricted to the regime of small local deformations. Rather by specifying a physically motivated Hamiltonian for *arbitrary* base(-step) parameters, our ansatz allows for realistic local structural transitions. For the simple case of a stretching force, we observed a transition from a twisted helix to a skewed ladder conformation. While our results suggest a similar structure for *S*-DNA as atomistic simulations [11], the DNA model studied in this paper, of course, cannot be used to rule out the alternate possibility of local strand separations [59–61].

In our opinion, the base(-pair) level provides a sensible compromise between the conceptual simplicity, the computational cost, and the degree of reality. Besides providing access to much larger scales than atomistic simulations, the derivation of such models from more microscopic considerations provides considerable insight. At the same time, they may serve to validate and unify analytical approaches aiming at (averaged) properties on larger scales [28–31,57]. Finally, we note that the applicability of linked-ellipsoid models is not restricted to the base-pair level of DNA as the same techniques can, for example, also be used to study chromatin [63–65].

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